# NON-DESTRUCTIVE TESTING: SAGNAC AND LDV

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#### OUTLINE

- 1. Optical methods for non-destructive testing
- 2. Motivation to study Sagnac and Mach-Zehnder interferometerbased vibrometries
- 3. Theoretical comparison of the two vibrometers
- 4. Conclusions and discussions



### OPTICAL METHODS FOR NDT

- Non-destructive testing (NDT):
  - Applications in automotive/Aerospace/Power/Oil and gas/Building industries
  - Includes: acoustic emission, electromagnetic testing, guided wave testing, thermal testing, ultrasonic testing ...
- Optical methods for ultrasound detection

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- Optical methods for ultrasound measurement is interesting: contactless measurement is great
- Typical solution: Laser Doppler vibrometry (LDV)
  based on Mach-Zehnder Interferometry





https://www.imperial.ac.uk/structural-integrity-healthmonitoring/research/structural-health-monitoring-/

#### MOTIVATION OF THE STUDY: CHALLENGES WITH LDV

- The velocity noise of Mach-Zehnder (MZ) interferometer-based vibrometry (Laser Doppler vibrometry, LDV) increases with frequency.
- Signal-to-noise ratio (SNR) is usually very low for ultrasound.

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Displacement noise and velocity noise: Sagnac and LDV

## MOTIVATION OF THE STUDY: SAGNAC VIBROMETER

- A very nice detection has been demonstrated with a Sagnac interferometry
  - Result is similar to those obtained from the contact methods
- Key information of the demonstration
  - Sagnac based measuring range: 1-10 MHz. The measured noise equivalent pressure is about 10 Pa over the operating band.
  - ~100ps to ~100ns laser pulse can generate pressure amplitudes achieving 10s or one hundred of Mpa.

Pelivanov, Ivan, et al. "A new fiber-optic non-contact compact laser-ultrasound scanner for fast non-destructive testing and evaluation of aircraft composites." Journal of Applied Physics 115.11 (2014): 113105.

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Ultrasound echo reconstruction using the Sagnac method



#### MOTIVATION OF THE STUDY

- Understand the limit of the Sagnac vibrometry.
- Check if we can realize similar techniques in integrated photonics.





The demonstrated Sagnac vibrometer

# WORKING PRINCIPLE: MACH-ZEHNDER VIBROMETER (HOMODYNE LDV)

**Blue:** reference light r(t) = a

**Red**: measurement light  $m(t) = b \cdot \exp(i\theta(t))$ 

Photocurrent:

 $I(t) = |m(t) + r(t)|^{2}$ =  $dc + 2|ab|\cos(\theta(t))$ Output signal  $s(t) = \theta(t)$ 

Retrieved signal s(t) is proportional to target displacement (Doppler effect)

$$s(t) = \frac{4\pi}{\lambda}d(t)$$



Moving target d(t)



#### WORKING PRINCIPLE: SAGNAC VIBROMETRY

**Blue:** CCW path; the target first, then the delay line;  $ccw(t) = a \cdot \exp(i\theta(t))$ 

**Red:** CW path; delay line first, then the target;  $cw(t) = b \cdot \exp(i\theta(t - \Delta T))$ 

 $\Delta T$  is the time delay brought by the delay line.



QWP: Quarter wave plate, PBS: Polarization beam splitter

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$$I(t) = dc + 2|ab|\cos(\theta(t) - \theta(t - \Delta T))$$

Output signal  $s(t) = \theta(t) - \theta(t - \Delta T)$ 

#### WORKING PRINCIPLE: SAGNAC VIBROMETRY

**Blue:** 
$$ccw(t) = a \cdot \exp(i\theta(t))$$
  
**Red:**  $cw(t) = b \cdot \exp(i\theta(t - \Delta T))$ 

From the retrieved signal s(t), we can obtain the target velocity:

**s**(*t*)

$$= \frac{4\pi}{\lambda} \times \left( d(t) - d(t - \Delta T) \right)$$
$$\approx \frac{4\pi}{\lambda} v(t) \Delta T$$

Retrieved signal s(t) is proportional to the target velocity v(t)



QWP: Quarter wave plate, PBS: Polarization beam splitter



### COMPARISON SAGNAC & MACH-ZEHNDER VIBROMETERS

Sagnac vibrometer	Mach-Zehnder vibrometer
Coherent/Incoherent light	Coherent light
Get velocity	Get displacement first
Requires delay line (meters long)	Not requires delay line
Bulky	Can be miniatured on a chip
Resistant to disturbance lights or scatters	Sensitive to disturbance lights





#### SENSITIVITY IN SHOT-NOISE LIMIT

- Assumption taken before
  - In **shot-noise limited** system.
  - Assuming the **power of the sensing light beam** is the same.
- Retrieving phase signal
  - In MZ vibrometry, the retrieved phase signal is  $s(t) = \frac{4\pi}{\lambda} d(t) \Leftrightarrow \frac{4\pi}{\lambda} D^F(\omega)$ 
    - Flat over the spectrum.
  - In Sagnac vibrometry,  $s(t) = \frac{4\pi}{\lambda} (d(t) d(t \Delta T)) \Leftrightarrow (1 e^{-j\omega\Delta T}) \cdot \frac{4\pi}{\lambda} D^F(\omega)$ 
    - Not flat because of filter  $(1 e^{-j\omega\Delta T})$ . At some frequency points, no signal s(t) is obtained.

#### ${\sf EFFECTIVE\ NOISE\ DENSITY\ OF\ SAGNAC\ AND\ MZ}$

• Sagnac vibrometry:

The noise density is not uniform. The noise level is a function of delay line length.

• MZ vibrometry:

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Noise density is uniform.

 Sagnac is not always better than MZ vibrometer with the same sensing power.

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- The sudden increase in phase noise of Sagnac at frequencies such as 2 MHz, 4 MHz and 6 MHz does not imply an actual increase in noise, but rather an absence of signal.
- When the vibration period of the object being measured coincides with the delay time of the delay line, the Sagnac interferometer is unable to detect a signal, that is  $\theta(t) = \theta(t \Delta T)$ , and then s(t) = 0
- Consequently, the phase noise appears to be effectively infinite.

#### DISCUSSION

- Why is Sagnac better than conventional LDV in the reported implementation?
  - Use very high optical power: up to 40 mW.
    - Eye safety limits to 1mW for visible light, 10mW for 1550 nm.
  - Great lens system, with N.A. = 0.5, capturing much reflection light.
    - The depth of focus will therefore be limited.
- Sagnac still has advantages in using broadband and low-coherent light sources and avoids unwanted reflection.
  - MZ-based method (not LDV) can also utilize similar method by using a long reference arm.
- Possible to implement Sagnac in a chip?
  - Not easy, because it needs long delay line (>10 m). Or work for very high frequency vibrations (GHz?).



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