

Comparison of Optical VCSEL Models on the Simulation of Oxide-Confined Devices

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Abstract—We compare the results of different optical vertical-cavity surface-emitting laser models on the position-dependent effects of thin oxide apertures. Both scalar and vectorial models as well as hybrid models are considered. Physical quantities that are compared are resonance wavelength, threshold material gain, and modal stability. For large device diameters and low-order modes, the agreement between the different models is quite good. Larger differences occur when considering smaller devices and higher order modes. It is also observed that the spread in the resonance wavelengths is smaller than that for the threshold material gain.

Index Terms—Distributed Bragg reflector lasers, laser modes, semiconductor device modeling, semiconductor lasers, surface-emitting lasers.

I. INTRODUCTION

IN RECENT YEARS, the characteristics of vertical-cavity surface-emitting lasers (VCSELs) have improved enormously, especially after the introduction of oxidized apertures

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to realize electrical and optical confinement. Today’s VCSELs show low-threshold current densities [1] and high output powers [2]. Moreover, their circular beam profiles and the possibility to integrate them into 2-D arrays [3] make them suitable candidates for short-range optical communications and optical interconnects.

In order to design the next generation of VCSELs with even better performance, it is imperative to be able to model the optical, electrical, and thermal effects that come into play in these devices. Specifically, the modeling of the optical field is quite challenging, since the Helmholtz equation is not separable in this case. Moreover, these structures can have large index contrasts, especially so for oxide-confined and airpost VCSELs. Over the years, a number of approaches have been proposed to model VCSELs, either scalar or vectorial, or approximate or rigorous. However, comparing these models and therefore validating their underlying assumptions has been difficult, if not impossible, since the published results obtained with these models are all for different VCSEL structures. It is the aim of the present paper to compare many of today’s important VCSEL models on the same benchmark problem, thereby quantifying the spread of results among the different models.

The rest of this paper is organized as follows. Section II gives a brief overview of each of the models involved in this comparison. The models are subdivided into scalar models, models with both a scalar and a vectorial implementation, hybrid scalar–vectorial models, and finally vectorial models. The names in parentheses occurring in each paragraph title will be used to refer to the results of that particular model. These names usually derive from an acronym or from the name of a university or company. The benchmark structure itself will be described in Section III. Subsequently, the simulation results of the models will be compared in Section IV. Finally, Section V summarizes our main conclusions. The numerical results of the simulations will be given in the Appendix, to facilitate comparison with future models.

II. OPTICAL VCSEL MODELS

A. Scalar Models

This class of models starts out from the scalar Helmholtz equation. In doing so, all polarization information is lost. This is usually not a problem, except when considering fields that have a relatively large transverse wavevector component, as is the case in higher order modes or smaller devices. The main advantage of these models is obviously their speed, making them

suitable design tools when the focus is more on capturing device trends rather than on obtaining numerically accurate results.

Hadley's Effective Index (EI) Model: In this model, implemented among others at Avalon Photonics, the lateral optical waveguide in the VCSEL is approximated by an EI step located at the radius of the oxide aperture. The index of the waveguide core is calculated from a field-weighted average of the different refractive indices in the VCSEL layer structure [4]. The index step to the cladding region is found by multiplying the core index with the relative wavelength shift of the cavity mode when the structure is oxidized ($\Delta n = n_{\text{core}} \cdot \Delta\lambda/\lambda$) [4]. The optical modes are linearly polarized (LP) modes, as found from the standard solution of a step index waveguide.

EI Method Using Eigenmodes (Chalmers): This model implemented at Chalmers University is also based on Hadley's EI model [5] for which the longitudinal field distribution is calculated by solving a 1-D eigenvalue equation. The transverse field distribution was obtained by solving

$$\frac{\partial E_{\text{transv}}}{\partial t} = \frac{ic}{2k_0 \langle \epsilon_i \rangle} \left(\frac{1}{r} \frac{\partial}{\partial r} r \frac{\partial}{\partial r} - \frac{m^2}{r^2} + k_0^2 \Delta \epsilon_{\text{eff}} \right) E_{\text{transv}} \quad (1)$$

where E_{transv} was assumed to have a time dependence according to

$$E_{\text{transv}} = E_{mn}(r) e^{i\Delta\omega_{mn}t}. \quad (2)$$

By inserting (2) into (1), we arrive at the following eigenvalue equation:

$$A_m E_{mn} = \Delta\omega_{mn} E_{mn}. \quad (3)$$

We can gather from (2) that the real and complex parts of the eigenvalue $\Delta\omega_{mn}$ are closely related to the modal cavity resonance and gain, respectively.

Prior to numerical calculations, the operator A_m in (3) was discretized uniformly by 100 points on a 10- μm mesh window. To calculate a mode profile with an accompanying eigenvalue took ~ 1 s. Calculations were done on a 333-MHz Pentium-II PC in a Matlab environment.

Effective Frequency (EF) Model: This model is also based on Hadley's EI model [4]–[6]. A comprehensive description can be found in [7]. The main differences to Hadley's model can be summarized as follows.

- 1) The optical frequency ω is considered to be a complex number. Its real and imaginary parts determine the modal wavelength and the decay constants, respectively, of the eigenmodes of the device.
- 2) The term $\omega^2 \epsilon(\mathbf{r}, \omega)$ occurring in the scalar wave equation is linearized around a real valued reference frequency ω_0 . For the device considered here, ω_0 was chosen to correspond to a vacuum wavelength of 980 nm.
- 3) Because the dielectric function $\epsilon(\mathbf{r}, \omega)$ may depend on the frequency ω , temporal dispersion is included.
- 4) Instead of having to solve a time-dependent, in-plane partial differential equation as in [4]–[6], we have to determine a complex valued eigenvalue ν of a time-independent ordinary differential equation, which gives the resonance wavelengths and decay constants of the modes of

the whole resonator. The complex valued eigenvalue ν is proportional to the frequency difference $\omega_0 - \omega$.

- 5) The derivation of the in-plane equation is based upon a variational principle by minimizing a functional.

By comparing with other models, it should be also noted that, in both the vertical direction (perpendicular to the epitaxial layers) and the in-plane direction (parallel to the layers), the simulation domain is treated as infinitely extended, and exact transparent boundary conditions are used. Additionally, continuity of both the electric field strength and its normal derivative is required at all interfaces between different materials.

The numerical procedure of locating the material gain where the imaginary part of ν vanishes takes about 1 s on a 667-MHz DEC-Alpha workstation, for the benchmark structure of Section III. The linearization with respect to frequency leads to slight deviations of the results from the exact value, even for a purely planar configuration.

Optimized-Waist Paraxial Eigenmodes Using a Cavity S-Matrix (PREVEU): In the Paraxial Radiation Eigenmodes for VCSEL Emulation (PREVEU) model developed at Science Applications International Corporation [8], [9], the cavity round-trip S-matrix is obtained analytically using a paraxial mode expansion with the mode waist as a free parameter. No longitudinal index-averaging, or separable approximations, are assumed. Distributed Bragg reflectors (DBRs) are modeled by equivalent hard mirrors, located at the effective phase penetration and the effective diffraction lengths, respectively, for the standing-wave condition and reflected wavefront computation. Wavefront "clipping" due to finite mirror radius, and gain guiding due to finite gain area, are evaluated analytically in terms of nondiagonal S-matrices. In treating apertures, losses from wide-angle scattering outside the paraxial propagation cone are computed, applying the Born approximation to the EM scattering theory. The aperture-induced phase-shift is computed by Schrödinger perturbation theory. Scattering losses overtake combined losses from all other factors at small apertures. Wave propagation between gain, aperture, and mirror elements is modeled by the uniform medium paraxial propagator, yielding simply a rescaling of the paraxial beam parameters with distance traveled. Finally, the diffracted and deformed wavefront is projected onto the original, obtaining the analytic expression for the round-trip matrix in terms of current aperture, mode waist, and cavity Fresnel number. Variation of the round trip eigenvalue with respect to the mode waist yields the mode structure analytically.

Execution time for obtaining the first 20 modes is less than 100 ms on a Pentium 500 machine. Computed results yielded excellent agreement with near-field profile measurements on a 780-nm etched mesa device.

B. Models With Scalar and Vectorial Implementation

These models can be either formulated in a scalar or vectorial way and are, therefore, potentially well suited to evaluate the necessity of a vectorial implementation.

Coupled Mode Model (Torino): In this model [10], [11], implemented at the Politecnico di Torino, Italy, the vectorial electromagnetic field is expanded on the continuous basis of the

TE and TM free space modes of a reference medium in cylindrical coordinates. These are expressed in terms of Bessel and trigonometric functions and are labeled by the continuous transverse wavevector k , and by the discrete azimuthal index m . In each longitudinally homogeneous layer of the device, the coupling between the expansion modes is determined by the perturbation to the reference refractive index induced by the device transverse structure. Through the formal solution of the coupled-mode equations, it is possible to define a relation between the electric field at any two positions of the resonator. The boundary conditions are set by the self-consistency between backward and forward waves at two arbitrary sections and define the threshold condition of each mode as the solution of an eigenvalue problem: eigenvalues are related to threshold gains and lasing frequencies of the modes, while the corresponding eigenvectors give the expansion coefficients and allow the reconstruction of the fields. The only approximation in this approach is the discretization of the continuous wavevector k . The adopted discretization step and the number of modes (k, m) included in the mode expansion fix the dimensions of the eigenvalue problem. Different azimuthal modes are coupled only in the case of noncircularly symmetric structures. We have implemented this model with Matlab on a Pentium 400 MHz PC and finding a laser mode for the benchmark structure takes about 4 min.

The same formalism can be applied by adopting a simplified scalar basis for the field expansion that can be derived from the vectorial basis in the TEM limit. In this way, a comparison between the vectorial treatment and the LP scalar approximation can be carried out and the range of validity of the scalar approach can be discussed. The size of the LP problem is reduced by a factor of 2 (TEM instead of TE and TM modes) which corresponds to a factor of 4 decrease in computational time.

Numerical Mode-Matching Method (UI-NMM): To find the vector modes of the VCSEL cavity, a numerical mode-matching method (NMM) [12] is used. The starting point of our method is similar to the approach described in [13]: the VCSEL structure is placed in a perfect conducting cylindrical waveguide and the modes of that perfect conducting waveguide are used as an expansion basis. An orthonormal basis is calculated from this expansion basis using the modified Gram-Schmidt algorithm. The finite-difference operators are then projected onto a smaller subspace. The projected operators no longer contain the field finite-difference operators. At the same time, this method avoids the calculation of the overlap integrals between the field and refractive index profiles. Thus, our formulation is not structure-dependent (in the sense that it is not limited to structures with only single step-index profiles) and permits the accurate modeling of VCSEL structures with complex permittivities of arbitrary transverse profiles. Furthermore, Krylov subspace techniques are used to improve computation speed. An efficient algorithm to obtain the resonant wavelength, quality factor, and “hot-cavity” threshold gain for each mode is derived. The details of the optical model are given in [14]. This solver was used in conjunction with a comprehensive rate-equation solver to model complex VCSEL structures [15].

The computational resources to run this code are fairly modest: on an Intel Celeron 366 MHz with 128 MB of RAM,

simulation times to find the characteristics of one mode (resonant wavelength, “hot-cavity” threshold gain) are on the order of a few seconds to a couple of minutes.

Using the NMM, a scalar formulation was also derived. It is observed that the results closely match the vector results, especially for the wavelength. The largest discrepancies were observed for small diameters ($d = 1$ and $2 \mu\text{m}$) when the aperture is at a standing-wave anti-node (position no. 5). In this case, the relative difference in wavelength values is still negligible but the relative difference in threshold gain values is 7.6% for $d = 2 \mu\text{m}$ and 5.2% for $d = 1 \mu\text{m}$. For most practical cases, the scalar version of our code is sufficient. Compared to the vector version, computation times are divided by eight and memory requirements are divided by four.

For the simulation results given in the rest of this paper, the vectorial version of the model was used.

C. Hybrid Models

These approaches combine both scalar and vectorial approaches to deal with different subproblems of the VCSEL model.

Weighted Index Method With Parasitic Mode Loss (WIMP): The Weighted Index Method with Parasitic mode loss (WIMP) is a semi-analytic, hybrid scalar–vector technique for computing the relevant optical mode data (e.g., wavelength, threshold gain, and confinement factor) of an oxide-apertured VCSEL [16]–[18]. The method is born out of a quasi-rigorous solution of Maxwell’s equations for an azimuthally symmetric layered geometry. For each eigenmode of the VCSEL, the total electric and magnetic vector fields are segregated into two parts: a separable portion and a nonseparable portion. This is the crux of the method.

The separable fields are defined such that they exactly solve Maxwell’s equations for an underlying separable VCSEL geometry. Both the separable fields and their associated separable VCSEL geometry are simultaneously computed using the Weighted Index Method (WIM). In practice, for the sake of efficiency, we make the “linearly polarized” mode approximation, thereby yielding a representation of the separable fields where only the dominant vector field component is considered. The explicit results of this calculation are, for each eigenmode: separable electric and magnetic fields, corresponding separable geometry, resonant wavelength, confinement factor, and threshold gain. Here, the threshold gain compensates for mirror and absorption loss, as well as the two optical loss mechanisms present in the separable geometry. Diffraction loss comes about due to the nonseparability of the real geometry, which is captured by the second part of the WIMP.

The nonseparable vector fields solve a set of Maxwell’s equations in the original VCSEL geometry but with an additional volumetric source current stemming from the separable fields. The volumetric source current depends on two things: the relative strength of the separable fields, and the difference between the separable geometry and the actual geometry. Physically, we may think of the nonseparable fields as being the fields radiated by the separable source fields to compensate for the “nonseparability” of the VCSEL geometry. This is a semi-analogous line of reasoning to Huygen’s principle for wave propagation.

We solve for the nonseparable fields by expanding them in a Fourier basis set in the longitudinal direction. In order to retain the full vector stature of these fields, we use two orthogonal basis sets: a transverse electric set and a transverse magnetic set. The strength of each Fourier component is solved exactly in closed form using standard electromagnetic techniques; the diffraction loss is computed concurrently. The explicit results of this calculation are, for each eigenmode, a Fourier representation of the nonseparable fields and the diffraction loss. Finally, the separable and nonseparable solutions are combined and the threshold gain is adjusted to account for *all* optical loss mechanisms: absorption, mirror, and diffraction.

D. Vectorial Models

It is the aim of these models to solve Maxwell's equation exactly, without resorting to any approximations other than a nonzero discretization length or a finite number of terms retained in a series expansion. Therefore, these models are slower than their scalar counterparts, but they are the only resort when studying polarization properties or when considering fields with a significant amount of nonparaxial propagation (higher order modes, small devices, etc.).

Method of Lines (MoL): The method of lines (MoL) has been used to solve the vectorial wave equation in cylindrical coordinates [19], [20]. The structure is divided into layers where the material parameters are constant in the axial direction. An arbitrary distribution of the permittivity in the radial direction is possible. The wave equation has been discretized in the radial direction and trigonometric functions have been introduced in the azimuthal direction. The refractive index can also be variable in the azimuthal direction. In this case, Fourier series can be used instead of one single trigonometric function [21].

In the direction of propagation, analytic solutions are considered. The relation between the electric and magnetic fields at the boundary of two layers can be expressed as a complex admittance. Then, the impedance/admittance transformation concept has been used to transform the admittance into a reference plane where an eigenvalue problem must be solved. The admittance transformation concept is an excellent method to analyze structures with several (hundreds!) of different layers. It is a stable procedure, which has been proven by several examples [22].

The optical gain is introduced as the imaginary part of the complex refractive index of the active region. The whole structure has been calculated for the condition that the imaginary part of the complex resonance frequency vanishes. After solving the eigenvalue problem, the wavelength of the resonator and the optical field can be calculated in the whole structure.

The modeling of the task presented in this paper (see Section III) took 15 min in Matlab on a Pentium II 333-MHz PC to calculate the wavelength and the optical gain of one mode.

Green's Function Model (Green): The Green's function approach is based upon a mode eigenvalue equation forcing the modal gain to equal the modal loss, thereby enforcing the semiclassical lasing condition for the modes. The eigenvalue is defined as the complex number multiplying the gain in order that the semiclassical lasing condition is satisfied [23]. The mode equation is formulated as an integral eigenvalue

equation incorporating the tensor Green's function of the VCSEL structure. This is done to take advantage of the fact that the Green's function can handle open boundaries in a natural way. The eigenvalue equation is discretized using the method of moments, resulting in a small, dense matrix eigenvalue problem that is rapidly solved. The slow part of the problem is evaluating the Green's function matrix elements between source and receiver "bricks." These matrix elements are calculated by separating the VCSEL structure into planar and nonplanar parts, assuming that the underlying VCSEL structure is planar. The Green's function for the planar part is calculated by expanding the source and receiver in plane waves and propagating the resulting plane wave fields through the structure. The Green's function for the nonplanar part (e.g., the oxide aperture) is calculated by treating the nonplanar regions as effective volumetric polarization sources in the eigenvalue equation, making the eigenvalue equation into a generalized eigenvalue equation. This calculation is difficult, but it need only be performed once for a wide range of VCSEL structures and gain configurations, which was the goal of this effort. The simulations presented here took roughly an hour for each mode on a DEC Alpha 533-MHz processor, but the modes may be recalculated for changing gain conditions in a matter of seconds.

Eigenmode Expansion With PML (CAMFR): In this approach, the structure is divided into sections with a constant refractive index profile along the propagation axis, and the field in each of these sections is expanded onto the eigenmodes of that particular section. In order to get a discrete set of radiation modes, the VCSEL is placed in a perfectly conducting metal cylinder. This cylinder is coated with a perfectly matched layer (PML), so as to eliminate the parasitic reflections from it, thereby effectively simulating an open structure [24]–[26]. Thanks to these absorbing boundary conditions, the cylinder can be placed much closer to the VCSEL, leading to a smaller computational volume and an improved computation time. At the interfaces between different sections, mode matching is used to decompose the field into the eigenmodes of the new section. This procedure ultimately gives rise to scattering matrices describing the top and the bottom half of the cavity. These matrices can be used to express the condition that the lasing mode should have a round-trip gain of unity. Wavelength and material gain are varied to achieve this. The entire approach is implemented in our simulation tool CAMFR [26]¹. The simulation results in this paper were obtained with a radius of the metal cylinder of $12-0.05j \mu\text{m}$ and 200 modes. Locating a lasing mode takes on the order of 5–10 min on a 250-MHz Ultrasparc II.

III. BENCHMARK STRUCTURE

The benchmark structure originated from a modeling exercise [27] in the European COST268 action, which is an open framework to facilitate the free flow of scientific ideas and results. Participation to this modeling exercise was completely open, and in effect also many non-European groups collaborated. In

¹Available: <http://camfr.sourceforge.net>.

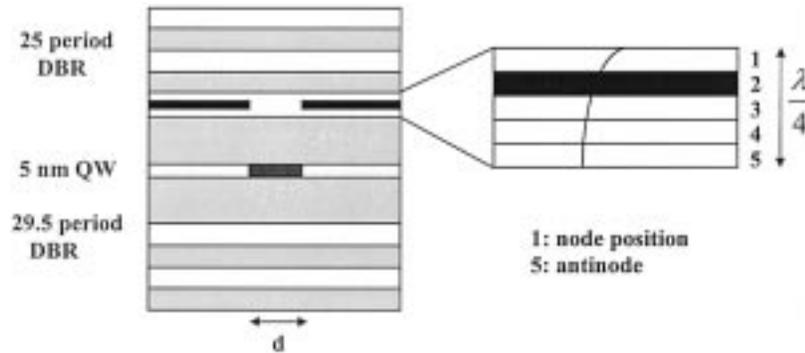


Fig. 1. Benchmark structure.

TABLE I
LAYER THICKNESSES AND REFRACTIVE INDICES OF
BENCHMARK STRUCTURE

	thickness	material	Index	
air		air	1	
24 pair DBR	69.49	GaAs	3.53	
	79.63	AlGaAs	3.08	
oxide window	69.49	GaAs	3.53	
	63.71-x	AlGaAs	3.08	
	15.93	AlAs	2.95	$r < d/2$
	x	AlOx	1.60	$r > d/2$
lambda cavity	136.49	GaAs	3.53	
	5.00	QW	$3.53 + j n_i$	$r < d/2$
			$3.53 - j 0.01$	$r > d/2$
29.5 pair DBR	79.63	AlGaAs	3.08	
	69.49	GaAs	3.53	
substrate		GaAs	3.53	

Pos	x
1	63.71
2	47.78
3	31.85
4	15.93
5	0.00

$$d = 1, 2, 4, 6, 8 \mu\text{m}$$

the end, ten different groups participated in the comparison, resulting in a significant cross section of the currently pursued VCSEL modeling research.

The structure itself is detailed in Fig. 1 and Table I. It is an AlGaAs VCSEL designed for operation around 980 nm. The bottom reflector consists of 29.5 pairs of AlGaAs–GaAs, while the top mirror has 25 pairs. In the lower $\lambda/4$ layer of the top mirror, a $\lambda/20$ -thick oxide aperture is placed. The gain in the 5-nm-thick quantum well (QW) is assumed to have a step-index profile with the same dimensions as the oxide aperture. Outside of the aperture, the QW exhibits loss. The structure is grown on a GaAs substrate. The parameters that are varied in the simulation are the position of the aperture with respect to the optical field (from '1—node position' to '5—antinode position' and the diameter of device (from 1 to 8 μm).

At this point, we want to point out that we do not include quantitative experimental verification for the modeling results. Experimental verification would not be as useful at it first seems, because a fabricated device will never have exactly the same geometry (layer thickness, material composition, etc.) as a proposed design, making exact quantitative comparisons awkward. Additionally, in real-life devices other aspects are at play, such as current flow and thermal effects, which are not captured by most of the models involved. We do not consider this to be a drawback of this paper, as it focuses solely on the optical aspects of VCSEL modeling, which is in itself already quite a broad and challenging topic.

IV. COMPARISON OF RESULTS

Fig. 2 shows the resonance wavelength for the fundamental mode (LP_{01} for the scalar modes, HE_{11} for the vectorial models) as a function of oxide position for a VCSEL with an 8- μm diameter. The top curve corresponds to the planar VCSEL, i.e., the central region extending toward infinity. All the curves are blue-shifted with respect to the planar results, since the outer region has a lower EI.

Generally, the trends of the different models agree very well (within 0.5 nm), which is to be expected for such a large structure. The PREVEU model, however, predicts a much smaller position-dependent resonance shift. Also note that the two curves for the scalar and vectorial version of the Torino model coincide. The same is true for the Chalmers and the EI model, since they are both variants of Hadley's EI model. It is also interesting to observe that there is no clear clustering between the scalar models (full lines) and the vectorial ones (dashed lines).

Fig. 3 shows the threshold material gain for the fundamental mode for the same 8- μm VCSEL. When the oxide moves toward the field minimum, confinement is lost in this particular VCSEL design and the threshold material gain goes up. Apart from the PREVEU model, there is a tendency for the vectorial models to predict higher thresholds than the scalar models. This is illustrated further in Fig. 4, which shows the relative threshold difference normalized to the arbitrarily chosen EF model, which also shows the lowest threshold. First of all, we can see that the spread in threshold is significantly higher than the spread in wavelength results. To study the differences between scalar and vectorial approaches, we first have to distinguish between scalar

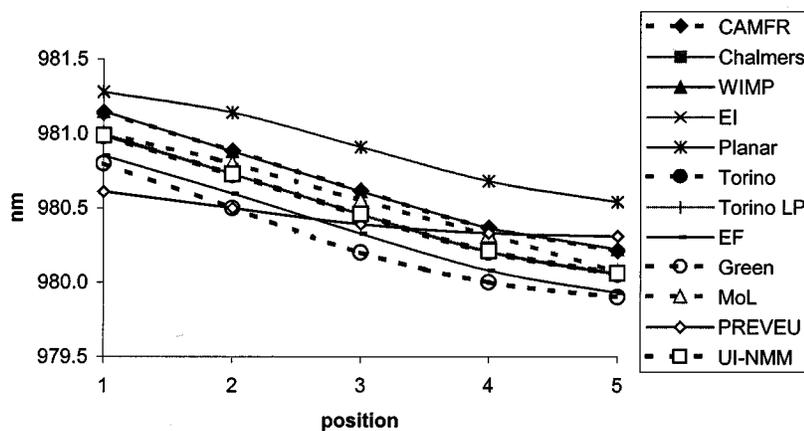


Fig. 2. Resonance wavelength for the fundamental mode as a function of oxide position for an 8- μ m-diameter VCSEL. (Full lines: scalar models. Dashed lines: vectorial models.)

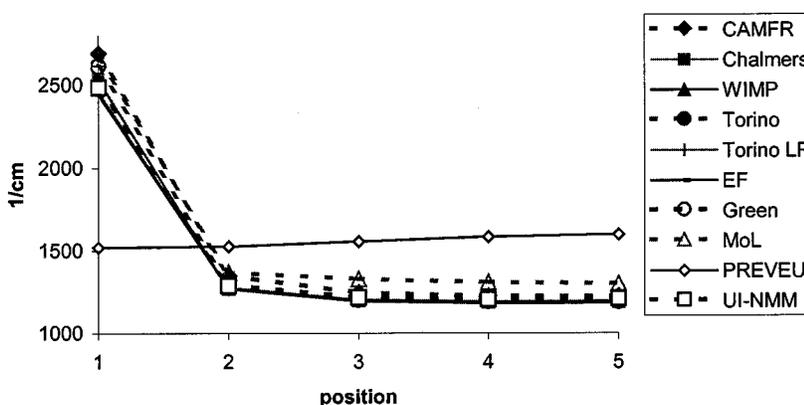


Fig. 3. Threshold material gain for the fundamental mode as a function of oxide position for an 8- μ m-diameter VCSEL.

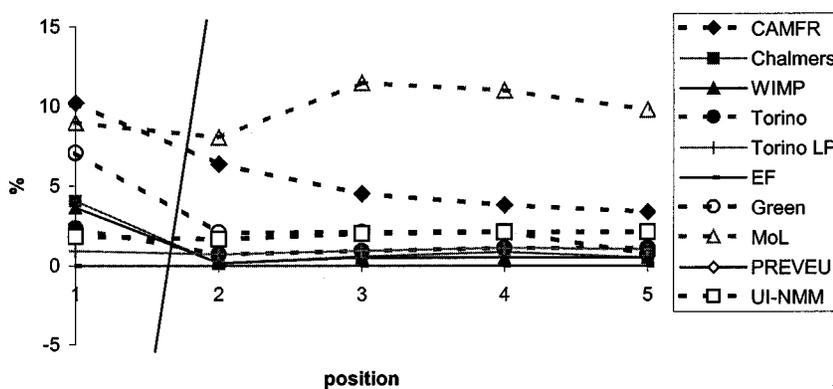


Fig. 4. Relative threshold material gain difference normalized to the EF model, for the fundamental mode as a function of oxide position for an 8- μ m-diameter VCSEL.

models that also imply a paraxial approximation (like the EI, Chalmers and EF models) and those that do not (WIMP, Torino LP, PREVEU, and the UI-NMM scalar version). The former are unable to take diffraction losses into account and therefore tend to predict lower thresholds, which can be seen from Fig. 4. The nonparaxial scalar models try to include these diffraction losses, but it is uncertain whether this is achieved as accurately as in a full vectorial model. Full-vectorial models (CAMFR, MoL, Green, Torino, and UI-NMM) take these diffraction losses fully into account, and therefore they typically predict higher thresh-

olds than the other models (see the dashed lines in Fig. 4). However, it is to be noted that the spread among the vectorial models is significantly higher than the spread among the scalar models. We attribute this to the influence of the boundary conditions, which becomes more prominent as radiation caused by diffraction propagates to the numerical boundary and can cause parasitic reflections [25].

When considering the scalar and the vectorial implementation of the Torino model, it can be seen that the differences are relatively minor. The largest difference occurs at the node posi-

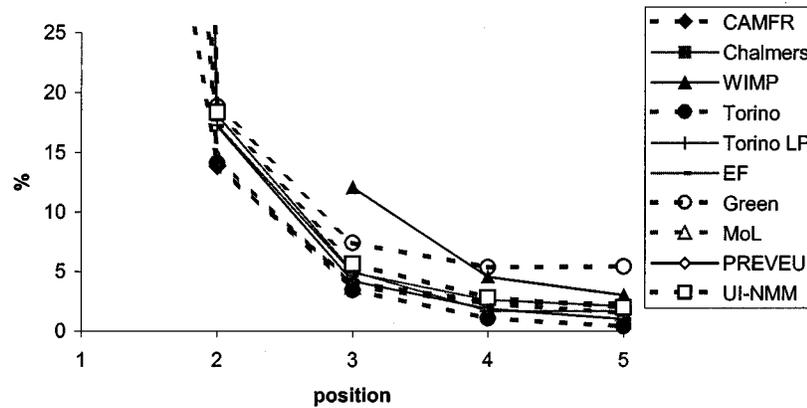


Fig. 5. Modal stability as a function of oxide position for an 8- μm -diameter VCSEL.

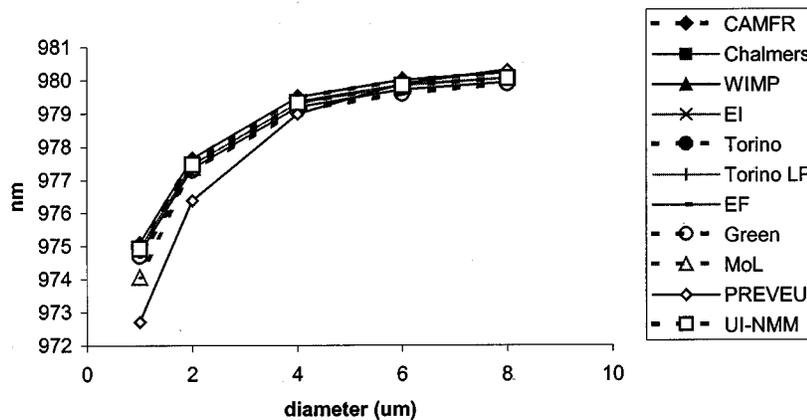


Fig. 6. Resonance wavelength for the fundamental mode as a function of diameter for an antinode oxide.

tion, where the vectorial version has a slightly higher threshold. These results seem to be typical for the Torino model, however. For the UI-NMM method, the difference between the scalar and the vectorial version is larger at the antinode position. These two models are the only nonparaxial scalar models that also have a vectorial version. Since comparing the differences between the scalar and the vectorial version gives different results for the different models, it would not be advisable to draw any firm conclusions on the ability of nonparaxial scalar models to accurately model diffraction loss.

Let us now consider simulation results on the first order mode. For scalar models, this is LP_{11} . For vectorial models, we choose TE_{01} . We could also have chosen TM_{01} or HE_{21} , since all three of these modes degenerate to LP_{11} in the scalar limit, but as the difference between these three modes is rather small, we restricted our parameter space to TE_{01} only.

In Fig. 5, we plot the modal stability, as defined by the percentage difference in threshold between the higher order mode and the fundamental one, written as

$$\frac{\text{Threshold first order} - \text{Threshold fundamental}}{\text{Threshold fundamental}}$$

For node oxides, the higher order mode suffers much more from the lack of confinement than the fundamental mode. This leads to an increased modal stability at the expense of a higher threshold for the fundamental mode. We also see

that comparing modal stability leads to an even higher spread in results than when comparing threshold gains or resonance wavelengths.

After keeping the diameter fixed and varying the oxide position, we now keep the oxide at the antinode position and vary the diameter. From Fig. 6, we see a decrease in lasing wavelength for decreasing aperture size. To further clarify the spread between the models, we plot in Fig. 7 the differences in predicted wavelength with regard to the EF model. The spread between the models is mostly of the same order of magnitude as in Fig. 2, although this time some models start to deviate from the general trend in going to smaller apertures (most notably MoL and PREVEU). As for the other models, the CAMFR results coincide very well with the WIMP model, and the EI, Chalmers, Torino, and UI-NMM models also give very similar results.

In Fig. 8, we plot the relative wavelength difference for the first-order mode. This time, the spread between the models is significantly higher and also increases as we move toward smaller diameters. The MoL results predict the longest wavelengths. The WIMP results no longer coincide with the CAMFR results and predict much shorter wavelengths. In spite of this larger spread in results, there is still no clear clustering between scalar and vectorial results, a conclusion consistent with the previous resonance wavelength calculations.

It is also interesting to consider the wavelength difference $\lambda_1 - \lambda_0$ between the first order and the fundamental mode. This

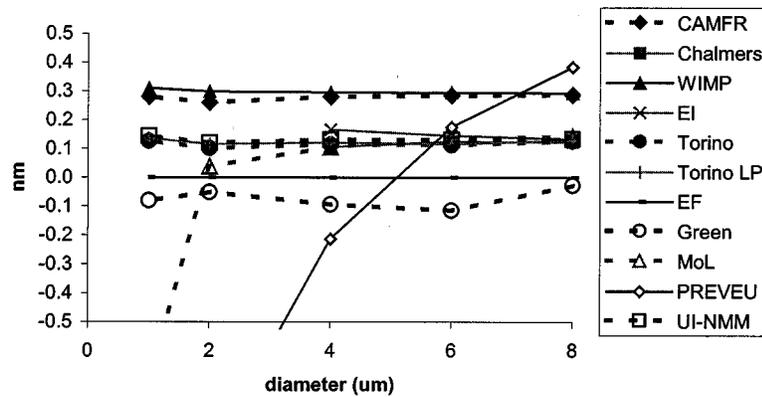


Fig. 7. Resonance wavelength difference with the EF model for the fundamental mode as a function of diameter for an antinode oxide.

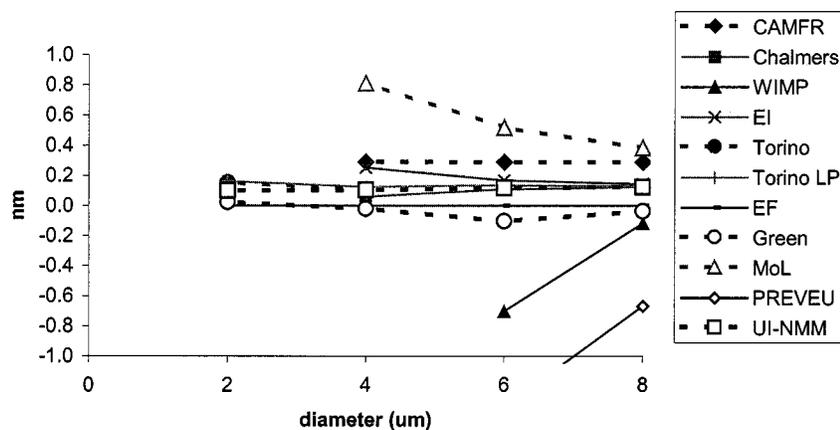


Fig. 8. Resonance wavelength difference with the EF model for the first-order mode as a function of diameter for an antinode oxide.

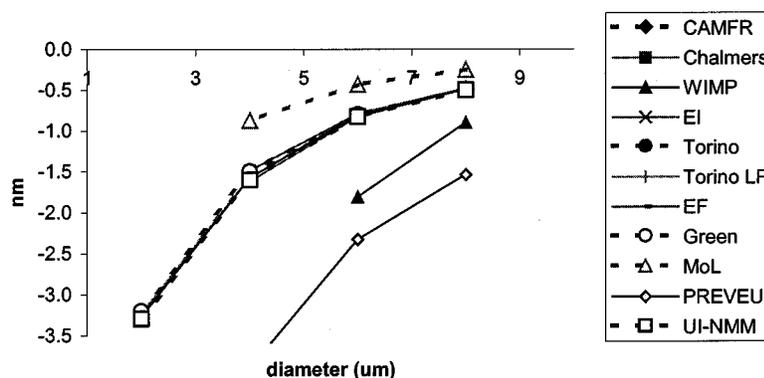


Fig. 9. Difference in resonance wavelength between the first order mode and the fundamental mode as a function of device diameter.

quantity depends mostly on the aperture geometry (diameter, thickness, position) and not so much on the longitudinal profile of the structure [14]. Hence, it focuses on the 2-D portion of the modeling and eliminates the influence of the longitudinal profile (some models might suffer from the discretization along the longitudinal direction). This wavelength splitting is an important parameter: as an example, it is possible to extract the mode diameter from this value [28]. Fig. 9 shows that, apart from the MoL, WIMP, and PREVEU results, the spread in this wavelength difference is a lot smaller than the spread in the individual wavelengths (roughly 0.1 nm instead of 0.5 nm).

Reducing the aperture size leads to a loss in confinement and higher thresholds, as can be seen in Fig. 10 (note the logarithmic scale). Once again, the differences between the models increase for smaller diameters, and vectorial models typically predict higher thresholds. Similar conclusions can be drawn from the relative threshold difference for the first-order mode in Fig. 11. The EF and EI models predict lower thresholds, because they do not take diffraction losses into account. The trend to show higher diffraction losses for smaller apertures is also much more pronounced for the vectorial models, and the relative spread between the vectorial models is, once again, much larger than be-

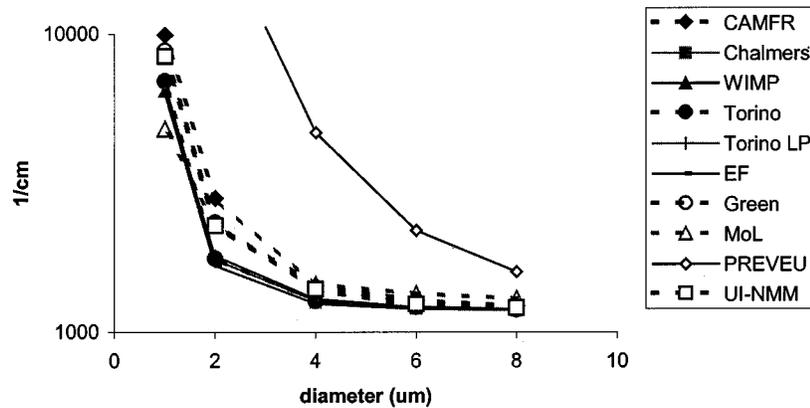


Fig. 10. Threshold material gain for the fundamental mode as a function of diameter for an antinode oxide. Note the logarithmic scale for the gain.

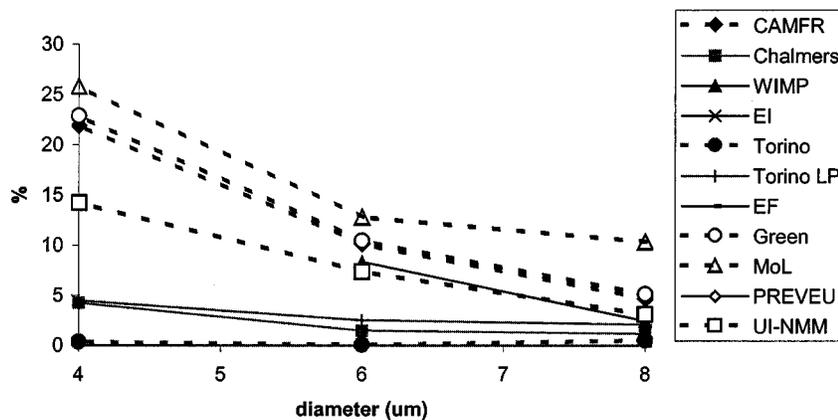


Fig. 11. Relative threshold material gain difference with the EF model for the first-order mode as a function of diameter for an antinode oxide.

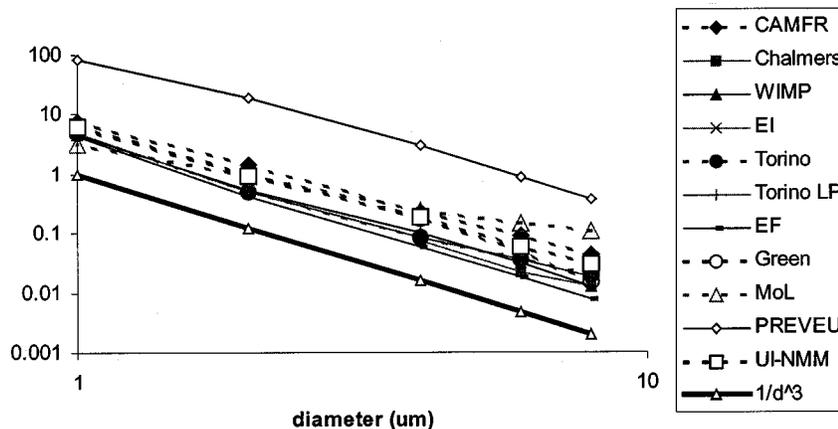


Fig. 12. Relative excess modal loss for the fundamental mode as a function of device diameter. Note the log-log scale and the slope coefficient of -3 .

tween the scalar models. The WIMP model follows the trend of the vectorial models quite well, although it has some difficulty in modeling structures smaller than $6 \mu\text{m}$ in diameter. The scalar and vectorial implementations of the Torino model give different results, but, strangely enough, the vectorial one predicts lower thresholds. This is explained by the fact that, in the scalar version of this model, the mirror reflectivity is a weighted average between the TE reflectivity and the slightly lower TM

reflectivity. This results in an underestimation of the true TE_{01} reflectivity, and hence an overestimation of the threshold gain for the scalar model.

From the results presented so far, we can also argue more clearly that parasitic reflections are an important aspect in explaining the spread between the vectorial models. Looking again at Figs. 10 and 11, we can see that this spread is larger for smaller diameters and higher order modes, precisely the situ-

TABLE II
NUMERICAL SIMULATION RESULTS FOR THE FUNDAMENTAL MODE IN AN 8- μm VCSEL

Lambda (nm)											
pos	CAMFR	Chalmers	WIMP	EI	Torino	Torino LP	EF	Green	MoL	PREVEU	UI-NMM
1	981.142	980.990	981.150	981.000	980.981	980.983	980.854	980.800	981.000	980.610	980.988
2	980.884	980.730	980.880	980.730	980.722	980.725	980.597	980.500	980.800	980.500	980.730
3	980.615	980.460	980.610	980.460	980.450	980.453	980.327	980.200	980.550	980.390	980.460
4	980.366	980.200	980.360	980.210	980.200	980.202	980.079	980.000	980.320	980.330	980.212
5	980.214	980.050	980.220	980.060	980.053	980.057	979.927	979.900	980.070	980.310	980.061

Threshold material gain (1/cm)											
pos	CAMFR	Chalmers	WIMP	EI	Torino	Torino LP	EF	Green	MoL	PREVEU	UI-NMM
1	2690	2540	2530		2498	2463	2441	2614	2660	1520	2486
2	1349	1270	1270		1277	1277	1268	1294	1370	1526	1289
3	1247	1200	1199		1204	1204	1193	1218	1330	1556	1217
4	1225	1190	1186		1193	1193	1180	1205	1310	1584	1205
5	1224	1190	1190		1197	1196	1184	1193	1300	1597	1209

TABLE III
NUMERICAL SIMULATION RESULTS FOR THE FIRST-ORDER MODE IN AN 8- μm VCSEL

Lambda (nm)											
pos	CAMFR	Chalmers	WIMP	EI	Torino	Torino LP	EF	Green	MoL	PREVEU	UI-NMM
1	980.995				980.714	980.716	980.549	980.500	980.890	979.500	980.692
2	980.508	980.350		980.350	980.344	980.347	980.219	980.100	980.650	979.280	980.349
3	980.167	980.000	979.570	980.000	979.999	980.004	979.879	979.800	980.390	979.000	980.006
4	979.890	979.730	979.430	979.730	979.718	979.723	979.602	979.500	980.150	978.830	979.727
5	979.726	979.560	979.320	979.580	979.559	979.565	979.438	979.400	979.820	978.770	979.562

Threshold material gain (1/cm)											
pos	CAMFR	Chalmers	WIMP	EI	Torino	Torino LP	EF	Green	MoL	PREVEU	UI-NMM
1	9637				13923	13826	14674	14918	7300	2055	14655
2	1536	1500			1487	1498	1486	1539	1570	2341	1526
3	1298	1260	1344		1247	1263	1243	1308	1380	2525	1286
4	1255	1210	1240		1206	1224	1202	1270	1340	2623	1239
5	1252	1210	1226		1202	1221	1196	1257	1320	2666	1233

Modal stability (%)											
pos	CAMFR	Chalmers	WIMP	EI	Torino	Torino LP	EF	Green	MoL	PREVEU	UI-NMM
1	258.3				82.1	461.3	501.1	470.8	174.4	35.2	489.5
2	13.9	18.1			14.1	17.3	17.2	18.9	14.6	53.4	18.4
3	4.1	5.0	12.1		3.4	4.9	4.2	7.4	3.8	62.3	5.7
4	2.4	1.7	4.6		1.1	2.6	1.9	5.4	2.3	65.6	2.8
5	2.3	1.7	3.0		0.4	2.1	1.0	5.4	1.5	66.9	2.0

ations where more radiation is propagating nonparaxially. For situations where we can assume the influence of parasitic reflections to be negligible, like for the fundamental mode in large devices, the spread between the models is very small.

Finally, we show in Fig. 12 the relative excess modal loss for the fundamental mode in the antinode oxide device. This quantity is defined as the relative difference $(g - g_{\text{planar}})/g_{\text{planar}}$ between the threshold material for the actual device

TABLE IV
NUMERICAL SIMULATION RESULTS FOR THE FUNDAMENTAL MODE IN AN ANTINODE OXIDE VCSEL

Lambda (nm)											
d	CAMFR	Chalmers	WIMP	EI	Torino	Torino LP	EF	Green	MoL	PREVEU	UI-NMM
8	980.214	980.050	980.220	980.060	980.053	980.057	979.927	979.900	980.070	980.310	980.061
6	980.000	979.840	980.010	979.860	979.828	979.831	979.715	979.600	979.850	979.890	979.847
4	979.475	979.300	979.490	979.360	979.309	979.315	979.194	979.100	979.300	978.980	979.326
2	977.612		977.650		977.453	977.467	977.351	977.300	977.390	976.380	977.471
1	975.061		975.090		974.906	974.916	974.780	974.700	974.070	972.710	974.924

Threshold material gain (1/cm)											
d	CAMFR	Chalmers	WIMP	EI	Torino	Torino LP	EF	Green	MoL	PREVEU	UI-NMM
8	1224	1190	1190		1197	1196	1184	1193	1300	1597	1209
6	1279	1200	1212		1217	1217	1196	1231	1350	2205	1244
4	1437	1260	1292		1275	1274	1245	1386	1450	4673	1399
2	2823		1806		1769	1756	1677	2340	2300	23954	2287
1	9925		6445		6945	6818	6278	8780	4813	96465	8422

TABLE V
NUMERICAL SIMULATION RESULTS FOR THE FIRST-ORDER MODE IN AN ANTINODE OXIDE VCSEL

Lambda (nm)											
d	CAMFR	Chalmers	WIMP	EI	Torino	Torino LP	EF	Green	MoL	PREVEU	UI-NMM
8	979.726	979.560	979.320	979.580	979.559	979.565	979.438	979.400	979.820	978.770	979.562
6	979.192	979.010	978.200	979.070	979.028	979.037	978.904	978.800	979.420	977.560	979.022
4	977.910	977.680		977.870	977.729	977.744	977.620	977.600	978.430	975.080	977.723
2	cut-off	cut-off		cut-off	974.231	974.237	974.08	974.100	cut-off	969.660	974.179
1	cut-off	cut-off		cut-off	cut-off	cut-off	cut-off	cut-off	cut-off	cut-off	cut-off

Threshold material gain (1/cm)											
d	CAMFR	Chalmers	WIMP	EI	Torino	Torino LP	EF	Green	MoL	PREVEU	UI-NMM
8	1252	1210	1225		1202	1221	1196	1257	1320	2666	1233
6	1357	1250	1335		1233	1263	1232	1361	1390	4977	1323
4	1696	1450			1396	1453	1391	1710	1750	14589	1589
2	cut-off	cut-off			21765	21578	16990	20679	cut-off	cut-off	26879
1	cut-off	cut-off			cut-off	cut-off	cut-off	cut-off	cut-off	cut-off	cut-off

Modal stability (%)											
d	CAMFR	Chalmers	WIMP	EI	Torino	Torino LP	EF	Green	MoL	PREVEU	UI-NMM
8	2.3	1.7	2.9		0.4	2.1	1.0	5.4	1.5	66.9	2.0
6	6.1	4.2	10.1		1.3	3.8	3.0	10.5	3.0	125.7	6.4
4	18.0	15.1			9.5	14.1	11.7	23.3	20.7	212.2	13.6
2					1130.4	1128.8	913.1	783.7			

and that of the planar device. This excess loss is mainly due to scattering losses at the oxide aperture. It has been observed that this quantity scales roughly as $1/d^3$ [14], [29], which

is confirmed by most of the models in the log-log plot of Fig. 12. Only the MoL curve tends to flatten a bit for large diameters.

V. CONCLUSION

Clearly, there is no such thing as the “best” VCSEL model suited for all purposes, as there is a whole spectrum of models that all trade off accuracy and calculation time, which are both very important parameters for practical use. When one is only interested in device trends, paraxial EI-like models can give very good results at unparalleled speeds. For more accurate simulations, there are nonparaxial scalar models or hybrid models that combine some aspects of scalar and vectorial techniques. For full accuracy, vectorial models are required, but these typically have much longer computation times and also need to deal adequately with the problems of parasitic reflections to achieve their full potential.

Although all these models are mostly able to predict the correct qualitative trends, quantitative results are not always the same. As far as resonance wavelength is concerned, these differences are often below 0.5 nm and can be considered minor. Larger differences occur when studying smaller oxide apertures or higher order modes. For the resonance wavelength, there is no clear clustering between scalar and vectorial models, which indicates that the scalar approach yields reliable results. Much larger discrepancies are observed in the threshold material gain, where deviations of 10%–30% are not uncommon. Again, the spread increases for smaller diameters and higher order modes. In these cases, the EI and EF models break down and predict lower thresholds, because they are unable to take diffraction losses into account. Vectorial models do incorporate these effects, and they typically predict higher thresholds. However, the spread among the vectorial gain results is much larger than the spread among the scalar results, most likely due to numerical influences like parasitic reflections at the boundaries of the computational domain. This seems to be an important aspect to take into account when developing models aiming for the “next” level of high numerical accuracy.

APPENDIX

This appendix contains the numerical results of the simulations. The data for the 8- μm VCSEL as a function oxide position can be found in Tables II and III, for the fundamental and first order mode respectively. The results as a function of size for an antinode oxide are summarized in Tables IV and V.

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